#### Operating Systems (Fall/Winter 2018)



# Synchronization Examples

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## Review

- Why we need synchronization?
- Race condition, critical section
- · Requirements: ME, Progress, Bounded waiting, Performance
- · Locks: acquire, release
  - implementation: test-and-set, compare-and-swap
- Semaphores: wait and signal, implementation
- · Condition variables: wait, signal, broadcast



# Classical Synchronization Problems

- Bounded-buffer problem
- Readers-writers problem
- Dining-philosophers problem



### Bounded-Buffer Problem

- Two processes, the producer and the consumer share n buffers
  - the producer generates data, puts it into the buffer
  - the consumer consumes data by removing it from the buffer
- The problem is to make sure:
  - the producer won't try to add data into the buffer if its full
  - the consumer won't try to remove data from an empty buffer
  - also call producer-consumer problem
- Solution:
  - n buffers, each can hold one item
  - semaphore mutex initialized to the value 1
  - semaphore full initialized to the value 0
  - semaphore empty initialized to the value N



## Bounded-Buffer Problem

The producer process:

```
do {
  //produce an item
  wait(empty);
  wait(mutex);
  //add the item to the buffer
   signal(mutex);
   signal(full);
} while (TRUE)
```



## Bounded Buffer Problem

• The consumer process:

```
do {
   wait(full);
   wait(mutex);
   //remove an item from buffer
   signal(mutex);
   signal(empty);
   //consume the item
} while (TRUE);
```



## Readers-Writers Problem

- A data set is shared among a number of concurrent processes
  - readers: only read the data set; they do not perform any updates
  - writers: can both read and write
- The readers-writers problem:
  - allow multiple readers to read at the same time (shared access)
  - only one single writer can access the shared data (exclusive access)
- Solution:
  - semaphore mutex initialized to 1
  - semaphore wrt initialized to 1
  - integer read\_count initialized to 0



### Readers-Writers Problem

The writer process

```
do {
  wait(wrt);
  //write the shared data
  signal(wrt);
} while (TRUE);
```



## Readers-Writers Problem

 The structure of a reader process do { wait(mutex); readcount++ ; if (readcount == 1) wait(wrt) ; signal(mutex) //reading data wait(mutex) ; readcount--; if (readcount == 0) signal(wrt); signal(mutex); } while(TRUE);



## Readers-Writers Problem Variations

- Two variations of readers-writers problem (different priority policy)
  - no reader kept waiting unless writer is updating data
  - once writer is ready, it performs write ASAP
- Which variation is implemented by the previous code example???
- Both variation may have starvation leading to even more variations
- If writer is in CS and n readers are waiting, one is on wrt, and n-1 are on mutex

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# Dining-Philosophers Problem

- Philosophers spend their lives thinking and eating
  - they sit in a round table, but don't interact with each other
- They occasionally try to pick up 2 chopsticks (one at a time) to eat
  - one chopstick between each adjacent two philosophers
  - · need both chopsticks to eat, then release both when done
  - Dining-philosopher problem represents multi-resource synchronization
- Solution (assuming 5 philosophers):
  - semaphore chopstick[5] initialized to 1





# Dining-Philosophers Problem

Philosopher i (out of 5): do { wait(chopstick[i]); wait(chopStick[(i+1)%5]); eat signal(chopstick[i]); signal(chopstick[(i+1)%5]); think } while (TRUE);

- What is the problem with this algorithm?
  - · deadlock



# Linux Synchronization

- Linux:
  - prior to version 2.6, disables interrupts to implement short critical sections
  - version 2.6 and later, fully preemptive
- Linux provides:
  - · semaphores
    - on single-cpu system, spinlocks replaced by enabling/disabling kernel preemption
  - Spinlocks
  - atomic integers
  - reader-writer locks



# Linux Synchronization

- Atomic variables
  - atomic\_t is the type for atomic integer
- Consider the variables
  - atomic t counter;

- int value;
- How?

```
static inline int fetch_and_add(int* variable, int value)
{
    __asm__ volatile("lock; xaddl %0, %1"
        : "+r" (value), "+m" (*variable) // input+output
        : // No input-only
        : "memory"
    );
    return value;
}
```

# THE WAS INVERSE

# POSIX Synchronization

- POSIX API provides
  - mutex locks
  - semaphores
  - condition variable
- Widely used on UNIX, Linux, and macOS



### POSIX Mutex Locks

Creating and initializing the lock

```
#include <pthread.h>
pthread_mutex_t mutex;

/* create and initialize the mutex lock */
pthread_mutex_init(&mutex,NULL);
```

Acquiring and releasing the lock

```
/* acquire the mutex lock */
pthread_mutex_lock(&mutex);
/* critical section */
/* release the mutex lock */
pthread_mutex_unlock(&mutex);
```



## POSIX Semaphores

- POSIX provides two versions named and unnamed.
- Named semaphores can be used by unrelated processes, unnamed cannot.



## POSIX Named Semaphores

Creating an initializing the semaphore:

```
#include <semaphore.h>
sem_t *sem;

/* Create the semaphore and initialize it to 1 */
sem = sem_open("SEM", O_CREAT, 0666, 1);
```

- Another process can access the semaphore by referring to its name
   SEM.
- Acquiring and releasing the semaphore:

```
/* acquire the semaphore */
sem_wait(sem);
/* critical section */
/* release the semaphore */
sem_post(sem);
```



## POSIX Unnamed Semaphores

Creating an initializing the semaphore:

```
#include <semaphore.h>
sem_t sem;

/* Create the semaphore and initialize it to 1 */
sem_init(&sem, 0, 1);
```

Acquiring and releasing the semaphore:

```
/* acquire the semaphore */
sem_wait(&sem);
/* critical section */
/* release the semaphore */
sem_post(&sem);
```



#### POSIX Condition Variables

 Since POSIX is typically used in C/C++ and these languages do not provide a monitor, POSIX condition variables are associated with a POSIX mutex lock to provide mutual exclusion: Creating and initializing the condition variable:

```
pthread_mutex_t mutex;
pthread_cond_t cond_var;

pthread_mutex_init(&mutex,NULL);
pthread_cond_init(&cond_var,NULL);
```



### POSIX Condition Variables

• Thread waiting for the condition a == b to become true:

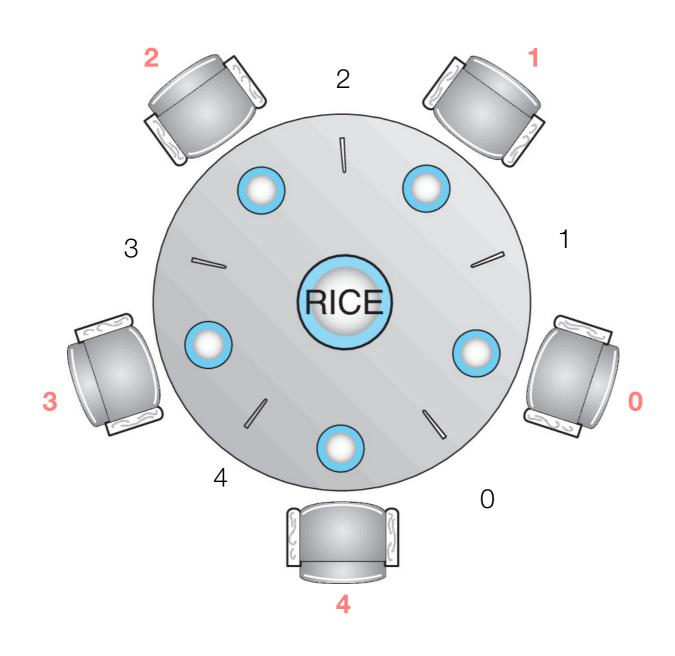
```
pthread_mutex_lock(&mutex);
while (a != b)
    pthread_cond_wait(&cond_var, &mutex);
pthread_mutex_unlock(&mutex);
release lock when wait
acquire lock when being signaled
```

Thread signaling another thread waiting on the condition variable:

```
pthread_mutex_lock(&mutex);
a = b;
pthread_cond_signal(&cond_var);
pthread_mutex_unlock(&mutex);
```



# Dining-Philosophers Problem in Practice





```
void *philosopher(void *v)
  Phil_struct *ps;
  int st;
  int t;
 ps = (Phil_struct *) v;
 while(1) {
   /* First the philosopher thinks for a random number of seconds */
    /* Now, the philosopher wakes up and wants to eat. He calls pickup
       to pick up the chopsticks */
    pickup(ps);
    /* When pickup returns, the philosopher can eat for a random number of
       seconds */
    /* Finally, the philosopher is done eating, and calls putdown to
       put down the chopsticks */
    putdown(ps);
```



# Solution 1: do nothing

```
void pickup(Phil_struct *ps)
{
   return;
}

void putdown(Phil_struct *ps)
{
   return;
}
```

```
O Philosopher O thinking for 2 seconds
0 Total blocktime:
                       0:
0 Philosopher 4 thinking for 2 seconds
O Philosopher 3 thinking for 1 second
O Philosopher 1 thinking for 2 seconds
0 Philosopher 2 thinking for 1 second
1 Philosopher 3 no longer thinking -- calling nickun()
1 Philosopher 3 eating for 2 seconds
1 Philosopher 2 no longer thinking -- calling pickup()
1 Philosopher 2 eating for 1 second
2 Philosopher 4 no longer thinking -- calling pickup()
2 Philosopher 4 eating for 1 second
2 Philosopher 1 no longer thinking -- calling pickup()
2 Philosopher 1 eating for 2 seconds
2 Philosopher 0 no longer thinking -- calling pickup()
2 Philosopher 0 eating for 1 second
2 Philosopher 2 no longer eating -- calling putdown()
2 Philosopher 2 thinking for 1 second
3 Philosopher 3 no longer eating -- calling putdown()
3 Philosopher 3 thinking for 1 second
3 Philosopher 2 no longer thinking -- calling pickup()
3 Philosopher 2 eating for 2 seconds
3 Philosopher 0 no longer eating -- calling putdown()
3 Philosopher 0 thinking for 2 seconds
3 Philosopher 4 no longer eating -- calling putdown()
3 Philosopher 4 thinking for 2 seconds
```

P2 and p3 cannot eat at the same time!



# Solution 2: A mutex for each chopstick

```
void putdown(Phil_struct *ps)
{
   Sticks *pp;
   int i;
   int phil_count;

   pp = (Sticks *) ps->v;
   phil_count = pp->phil_count;

   pthread_mutex_unlock(pp->lock[(ps->id+1)%phil_count]); /* unlock right stick */
   pthread_mutex_unlock(pp->lock[ps->id]); /* unlock left stick */
}
```



# Solution 2: A mutex for each chopstick

```
0 Total blocktime:
                       0:
0 Philosopher 0 thinking for 2 seconds
O Philosopher 1 thinking for 2 seconds
0 Philosopher 2 thinking for 1 second
0 Philosopher 3 thinking for 2 seconds
0 Philosopher 4 thinking for 1 second
1 Philosopher 2 no longer thinking -- calling pickup()
1 Philosopher 2 eating for 2 seconds
1 Philosopher 4 no longer thinking -- calling pickup()
1 Philosopher 4 eating for 1 second
2 Philosopher 0 no longer thinking -- calling pickup()
2 Philosopher 1 no longer thinking -- calling pickup()
2 Philosopher 3 no longer thinking -- calling pickup()
2 Philosopher 4 no longer eating -- calling putdown()
2 Philosopher 4 thinking for 1 second
3 Philosopher 2 no longer eating -- calling putdown()
3 Philosopher 2 thinking for 2 seconds
3 Philosopher 1 eating for 2 seconds
3 Philosopher 3 eating for 2 seconds
3 Philosopher 4 no longer thinking -- calling pickup()
5 Philosopher 3 no longer eating -- calling putdown()
5 Philosopher 3 thinking for 1 second
5 Philosopher 1 no longer eating -- calling putdown()
5 Philosopher 1 thinking for 1 second
```

Could be deadlock, but ...



## Solution 3: Show how deadlock occurs

```
void pickup(Phil struct *ps)
  Sticks *pp;
  int phil count;
  pp = (Sticks *) ps->v;
  phil count = pp->phil count;
  pthread mutex lock(pp->lock[ps->id]);
                                          /* lock up left stick */
  sleep(3);
  pthread mutex lock(pp->lock[(ps->id+1)%phil count]); /* lock up right stick */
 0 Philosopher 0 thinking for 1 second
 O Philosopher 2 thinking for 3 seconds
 O Philosopher 3 thinking for 1 second
 O Philosopher 4 thinking for 2 seconds
 0 Philosopher 1 thinking for 1 second
 O Total blocktime:
                       0: 0
 1 Philosopher 3 no longer thinking -- calling pickup()
 1 Philosopher 1 no longer thinking -- calling pickup()
 1 Philosopher 0 no longer thinking -- calling pickup()
 2 Philosopher 4 no longer thinking -- calling pickup()
 3 Philosopher 2 no longer thinking -- calling pickup()
 10 Total blocktime:
                      42 :
```



# Solution 4: An asymmetrical solution

 only odd philosophers start left-hand first, and even philosophers start right-hand first. This does not deadlock.

```
void pickup(Phil struct *ps)
  Sticks *pp;
  int phil count;
  pp = (Sticks *) ps->v;
  phil count = pp->phil count;
  if (ps->id % 2 == 1) {
    pthread mutex lock(pp->lock[ps->id]);
                                                 /* lock up left stick */
    pthread mutex lock(pp->lock[(ps->id+1)%phil count]); /* lock right stick */
  } else {
    pthread mutex lock(pp->lock[(ps->id+1)%phil count]); /* lock right stick */
    pthread mutex lock(pp->lock[ps->id]);
                                                 /* lock up left stick */
void putdown(Phil struct *ps)
  Sticks *pp;
  int i;
  int phil count;
 pp = (Sticks *) ps->v;
  phil count = pp->phil count;
  if (ps->id % 2 == 1) {
   pthread mutex unlock(pp->lock[(ps->id+1)%phil count]); /* unlock right stick */
    pthread mutex unlock(pp->lock[ps->id]); /* unlock left stick */
  } else {
   pthread mutex unlock(pp->lock[ps->id]); /* unlock left stick */
   pthread_mutex_unlock(pp->lock[(ps->id+1)%phil_count]); /* unlock right stick */
```